

Compilers

- Two goals:
 - Correctness
 - Speed

 Complications in code generation come from trying to be fast as well as correct

Two assumptions:

 Execution is sequential; control moves from one point in a program to another in a well-defined order

2. When a procedure is called, control always returns to the point immediately after the call

An invocation of procedure P is an activation of P

- The *lifetime* of an activation of P is
 - All the steps to execute P
 - Including all the steps in procedures P calls

 The *lifetime* of a variable x is the portion of execution in which x is defined

- Note that
 - Lifetime is a dynamic (run-time) concept
 - Scope is a static concept

Observation

When P calls Q, then Q returns before P returns

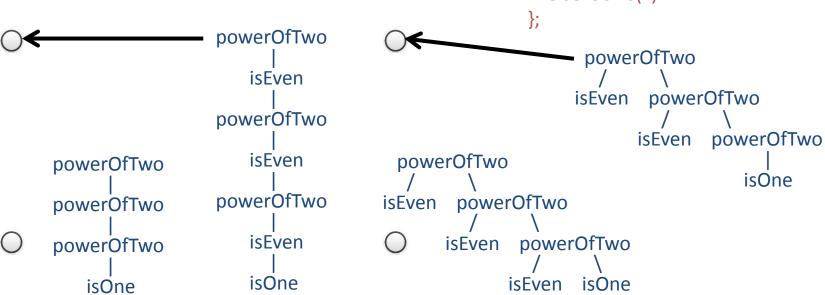
Lifetimes of procedure activations are properly nested

Activation lifetimes can be depicted as a tree

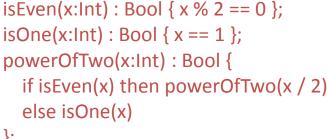
```
Class Main {
    g(): Int { 1 };
    f(): Int { g() };
    main(): Int {{ g(); f(); }};
}
```

```
Class Main {
    g() : Int { 1 };
    f(x:Int): Int { if x = 0 then g() else f(x - 1) fi};
    main(): Int {{f(3); }};
}
```

The powerOfTwo() function, shown to the right, returns true if its argument is a power of two, false otherwise. What is the activation tree for powerOfTwo(4)?



Activations



isOne

The activation tree depends on run-time behavior

The activation tree may be different for every program input

 Since activations are properly nested, a stack can track currently active procedures

```
Class Main {
    g(): Int { 1 };
    f(): Int { g() };
    main(): Int {{ g(); f(); }};
}
```

Low Address Code Memory Stack **High Address**