



Compilers

Cool Semantics II

- Informal semantics of **new T**
 - Allocate locations to hold all attributes of an object of class **T**
 - Essentially, allocate a new object
 - Set attributes with their default values
 - Evaluate the initializers and set the resulting attribute values
 - Return the newly allocated object

- For each class A there is a default value D_A
 - $D_{\text{int}} = \text{Int}(0)$
 - $D_{\text{bool}} = \text{Bool}(\text{false})$
 - $D_{\text{string}} = \text{String}(0, \text{“”})$
 - $D_A = \text{void}$ (for any other class A)

- For a class A we write

$\text{class}(A) = (a_1 : T_1 \leftarrow e_1, \dots, a_n : T_n \leftarrow e_n)$ where

- a_i are the attributes (including the inherited ones)
- T_i are the attributes' declared types
- e_i are the initializers

$$\begin{array}{l}
T_0 = \text{if } (T == \text{SELF_TYPE} \text{ and } \text{so} = X(\dots)) \text{ then } X \text{ else } T \\
\text{class}(T_0) = (a_1 : T_1 \leftarrow e_1, \dots, a_n : T_n \leftarrow e_n) \\
l_i = \text{newloc}(S) \text{ for } i = 1, \dots, n \\
v = T_0(a_1 = l_1, \dots, a_n = l_n) \\
S_1 = S[D_{T_1}/l_1, \dots, D_{T_n}/l_n] \\
E' = [a_1 : l_1, \dots, a_n : l_n] \\
v, E', S_1 \vdash \{ a_1 \leftarrow e_1; \dots; a_n \leftarrow e_n; \} : v_n, S_2 \\
\hline
\text{so, } E, S \vdash \text{new } T : v, S_2
\end{array}$$

- The first three steps allocate the object
- The remaining steps initialize it
 - By evaluating a sequence of assignments
- State in which the initializers are evaluated
 - Self is the current object
 - Only the attributes are in scope (same as in typing)
 - Initial values of attributes are the defaults

- Informal semantics of $e_0.f(e_1, \dots, e_n)$
 - Evaluate the arguments in order e_1, \dots, e_n
 - Evaluate e_0 to the target object
 - Let X be the dynamic type of the target object
 - Fetch from X the definition of f (with n args.)
 - Create n new locations and an environment that maps f 's formal arguments to those locations
 - Initialize the locations with the actual arguments
 - Set $self$ to the target object and evaluate f 's body

- For a class A and a method f of A (possibly inherited):

$\text{impl}(A, f) = (x_1, \dots, x_n, e_{\text{body}})$ where

- x_i are the names of the formal arguments
- e_{body} is the body of the method

$$\begin{array}{l}
 \text{so, } E, S \vdash e_1 : v_1, S_1 \\
 \text{so, } E, S_1 \vdash e_2 : v_2, S_2 \\
 \dots \\
 \text{so, } E, S_{n-1} \vdash e_n : v_n, S_n \\
 \text{so, } E, S_n \vdash e_0 : v_0, S_{n+1} \\
 v_0 = X(a_1 = l_1, \dots, a_m = l_m) \\
 \text{impl}(X, f) = (x_1, \dots, x_n, e_{\text{body}}) \\
 l_{x_i} = \text{newloc}(S_{n+1}) \text{ for } i = 1, \dots, n \\
 E' = [a_1 : l_1, \dots, a_m : l_m][x_1/l_{x_1}, \dots, x_n/l_{x_n}] \\
 S_{n+2} = S_{n+1}[v_1/l_{x_1}, \dots, v_n/l_{x_n}] \\
 v_0, E', S_{n+2} \vdash e_{\text{body}} : v, S_{n+3} \\
 \hline
 \text{so, } E, S \vdash e_0.f(e_1, \dots, e_n) : v, S_{n+3}
 \end{array}$$

What is the final value of S_5 in the dispatch of `obj.foo(i)` below?

so, $[i:l_i], S_1 \vdash i : 3, S_2$
so, $[i:l_i], S_2 \vdash \text{obj} : C(a = l_{\text{obj_a}}), S_3$
 $\text{impl}(C, \text{foo}) = (x, x + a)$
 $l_x = \text{newloc}(S_3)$
 $S_4 = S_3[3/l_x]$
 $\frac{C(a = l_{\text{obj_a}}), [a:l_{\text{obj_a}}][x/l_x], S_4 \vdash x + a : 4, S_5}{\text{so, } [i:l_i], [l_{\text{obj_a}} \leftarrow 1, l_i \leftarrow 3] \vdash \text{obj.foo}(i) : 4, S_5}$

Cool Semantics II

```
Class C {  
    a: Int <- 0;  
    foo(x: Int) : Int { x + a };  
};
```

- ☐ $[l_i \leftarrow 3]$
- ☐ $[l_{\text{obj_a}} \leftarrow 1, l_i \leftarrow 3]$
- ☐ $[l_{\text{obj_a}} \leftarrow 1, l_i \leftarrow 3, l_x \leftarrow 3]$
- ☐ It cannot be determined from the information given.

- The body of the method is invoked with
 - **E** mapping formal arguments and self's attributes
 - **S** like the caller's except with actual arguments bound to the locations allocated for formals
- The notion of the frame is implicit
 - New locations are allocated for actual arguments
- The semantics of static dispatch is similar

Operational rules do not cover all cases
Consider the dispatch example:

...
so, $E, S_n \vdash e_0 : v_0, S_{n+1}$
 $v_0 = X(a_1 = l_1, \dots, a_m = l_m)$
 $\text{impl}(X, f) = (x_1, \dots, x_n, e_{\text{body}})$
...

- There are some runtime errors that the type checker does not prevent
 - A dispatch on void
 - Division by zero
 - Substring out of range
 - Heap overflow
- In such cases execution must abort gracefully
 - With an error message, not with a segfault

- Operational rules are very precise & detailed
 - Nothing is left unspecified
 - Read them carefully
- Most languages do not have a well specified operational semantics
- When portability is important an operational semantics becomes essential